



MICRO-CREDENTIAL

LAND MANAGEMENT IN CENTRAL ASIA

14.- Radar and Laser Remote Sensing

Radar and LiDAR Review

LM-W14-V98

Concepts, interpretation, applications, advantages, limitations, and sensor choice for land management

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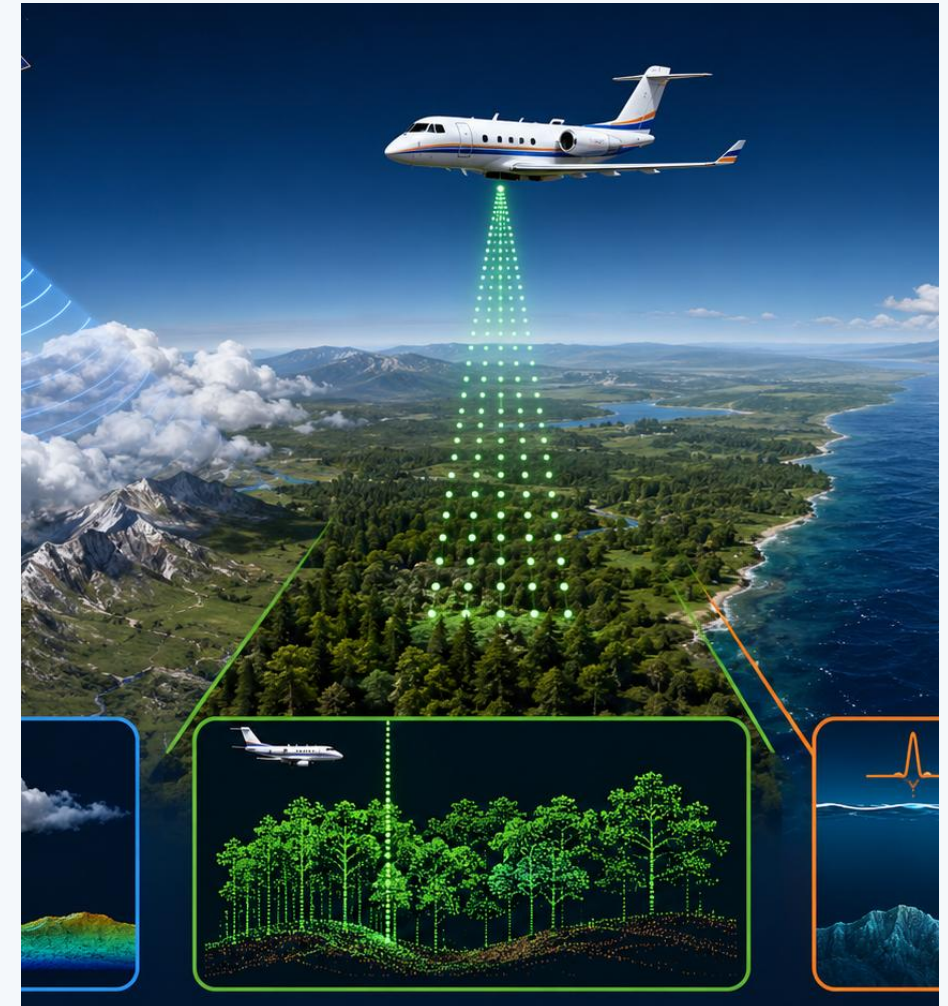
By the end of this review, students should be able to:

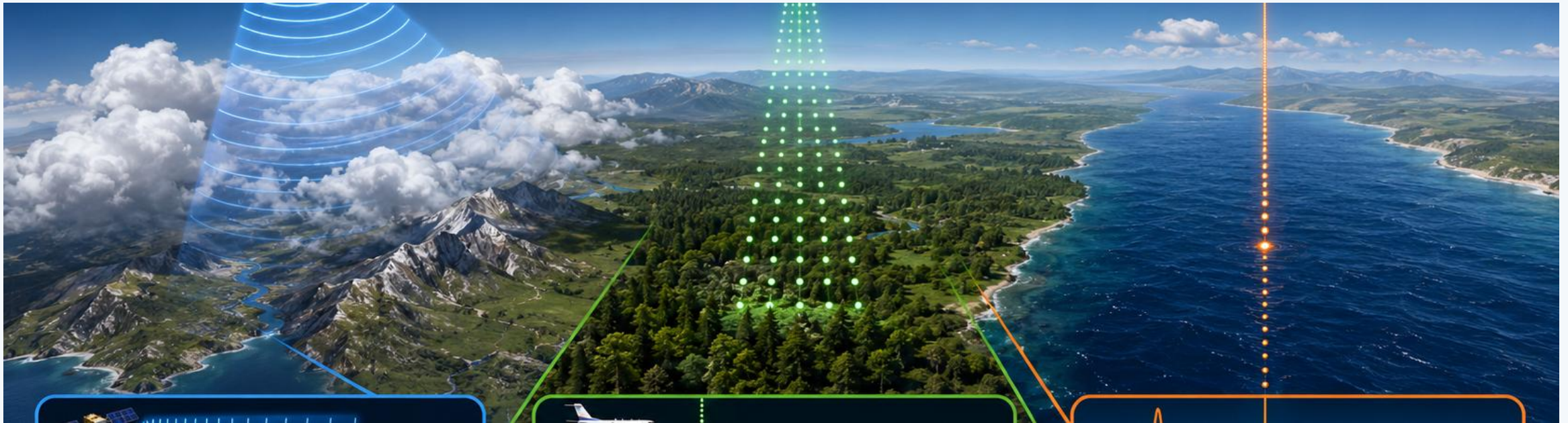
Recall the operating principles of radar and LiDAR systems.
Explain how backscatter, time-of-flight, and point clouds are interpreted.

Compare applications in land, water, terrain, vegetation, and infrastructure studies.

Recognize common limitations, errors, and data-processing needs.

Choose a suitable sensor or integrated workflow for a practical land-management task.





1. Emit energy

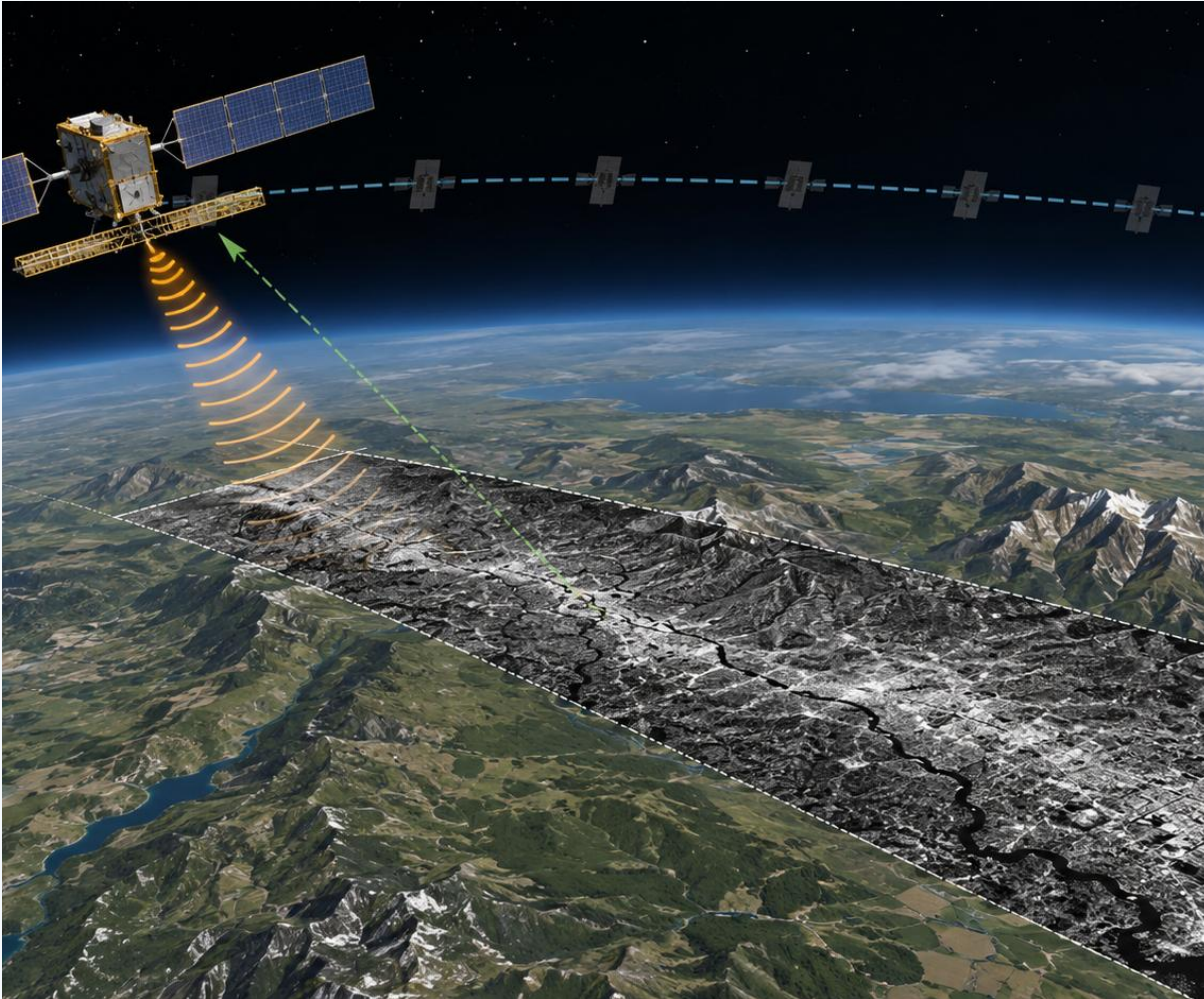
2. Hit surface

3. Return signal

4. Record data

5. Interpret

Radar and LiDAR are active systems: they do not only “look”; they send energy and measure the returned signal.



Key interpretation controls

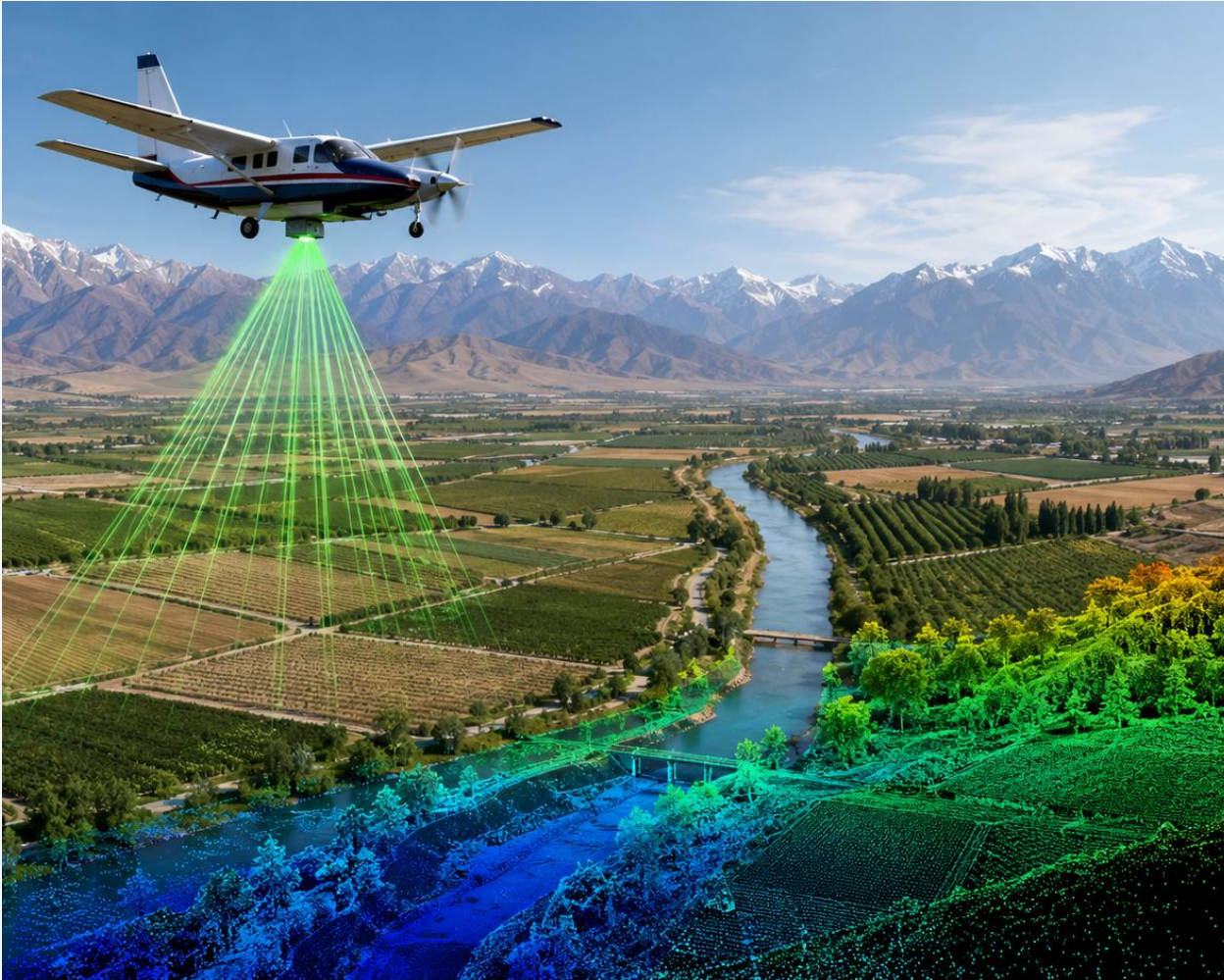
Wavelength: controls penetration and interaction with surface elements.

Polarization: describes orientation of transmitted and received waves.

Incidence angle: affects brightness, shadow, layover, and visibility of slopes.

Backscatter: stronger from rough, moist, or complex structures; weaker from smooth water.

Concept based on NASA Earthdata SAR basics and NASA ARSET SAR training.



Core process

A laser pulse is emitted toward the surface.

Travel time is converted into distance using time-of-flight.

GNSS and IMU record platform position and orientation.

Many measured points form a 3D point cloud.

Classified points support DEM, DSM, canopy and object extraction.

Concept based on NASA GEDI/GEDI LiDAR information and USGS 3DEP materials.

Main products: what do we get from each system?

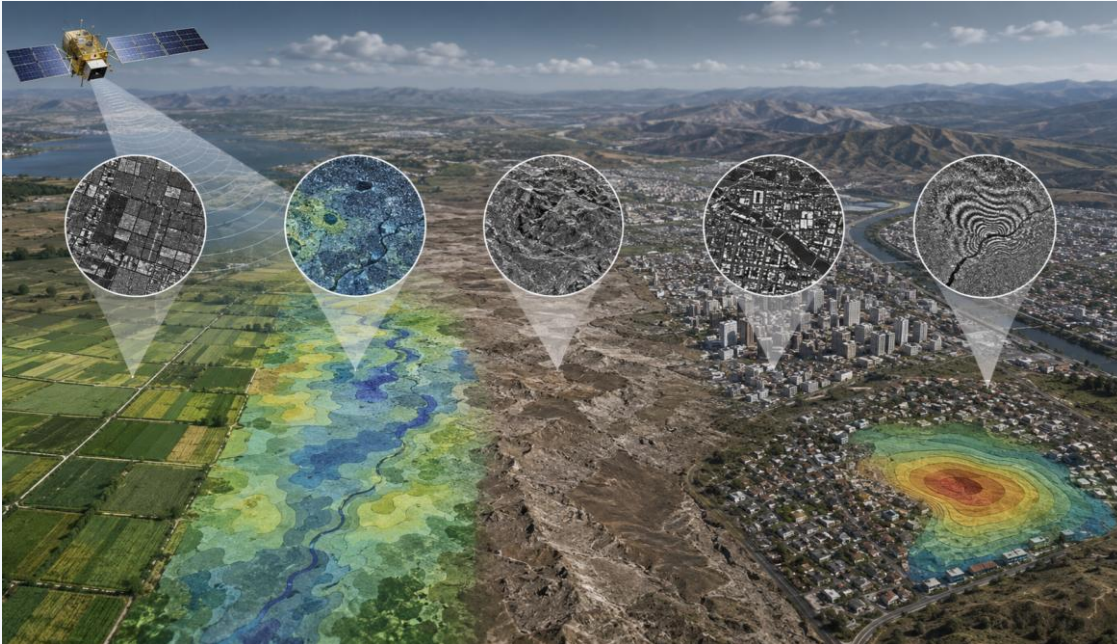
Radar products

- Backscatter intensity images
- Multi-polarization composites
- Coherence maps
- InSAR deformation products
- Flood or surface-water masks
- Soil moisture and crop structure indicators

LiDAR products

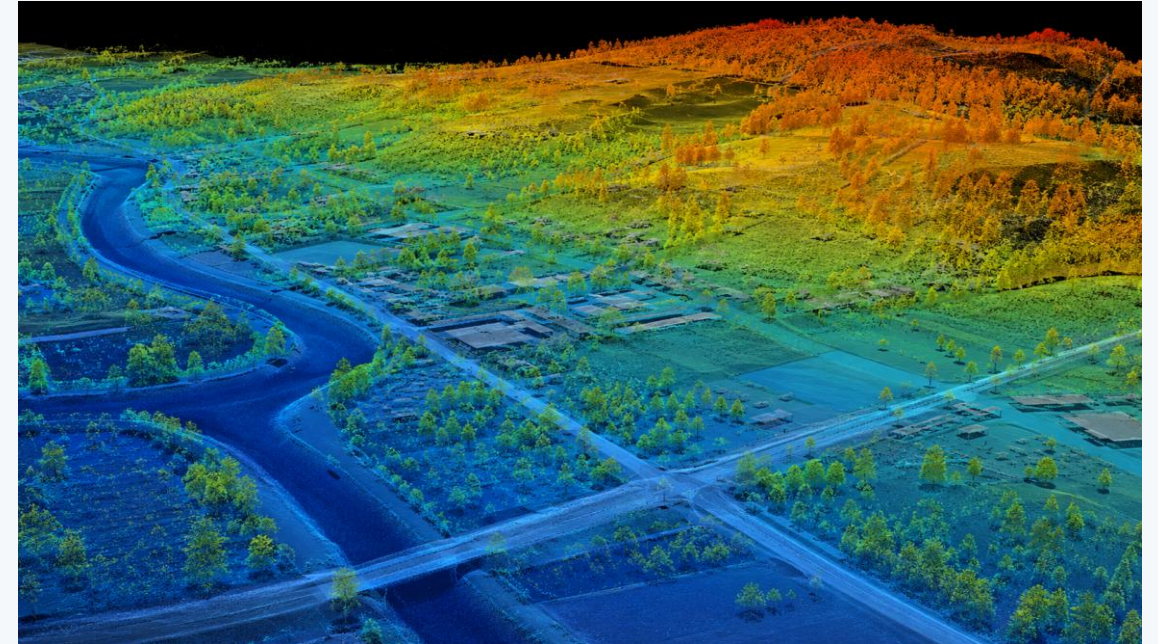
- Raw and classified point clouds
- Digital Terrain Models / DEMs
- Digital Surface Models / DSMs
- Canopy height models
- Contours, slope, aspect, hillshade
- 3D building and infrastructure layers

Review rule: first identify the product you need, then select the sensor.



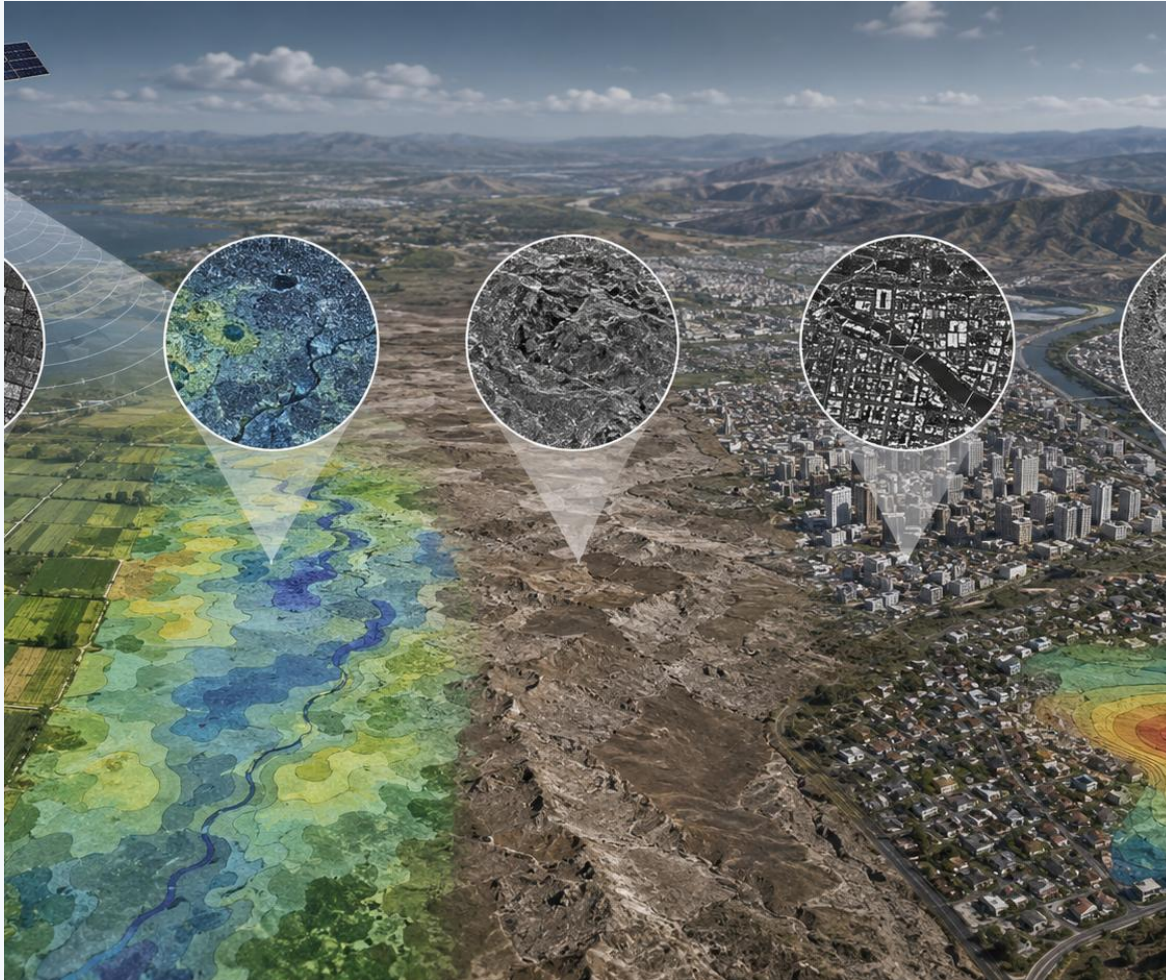
Radar image logic

Bright: strong backscatter from rough, moist or complex targets. Dark: smooth water, radar shadow or low return.



LiDAR image logic

Elevation colour, density, and point class show terrain, vegetation, buildings, embankments and drainage features.



Agriculture

crop structure, irrigation condition, moisture clues

Land cover

built-up areas, forests, roughness, bare soil

Degradation

erosion-prone surfaces, salinity-prone zones with supporting data

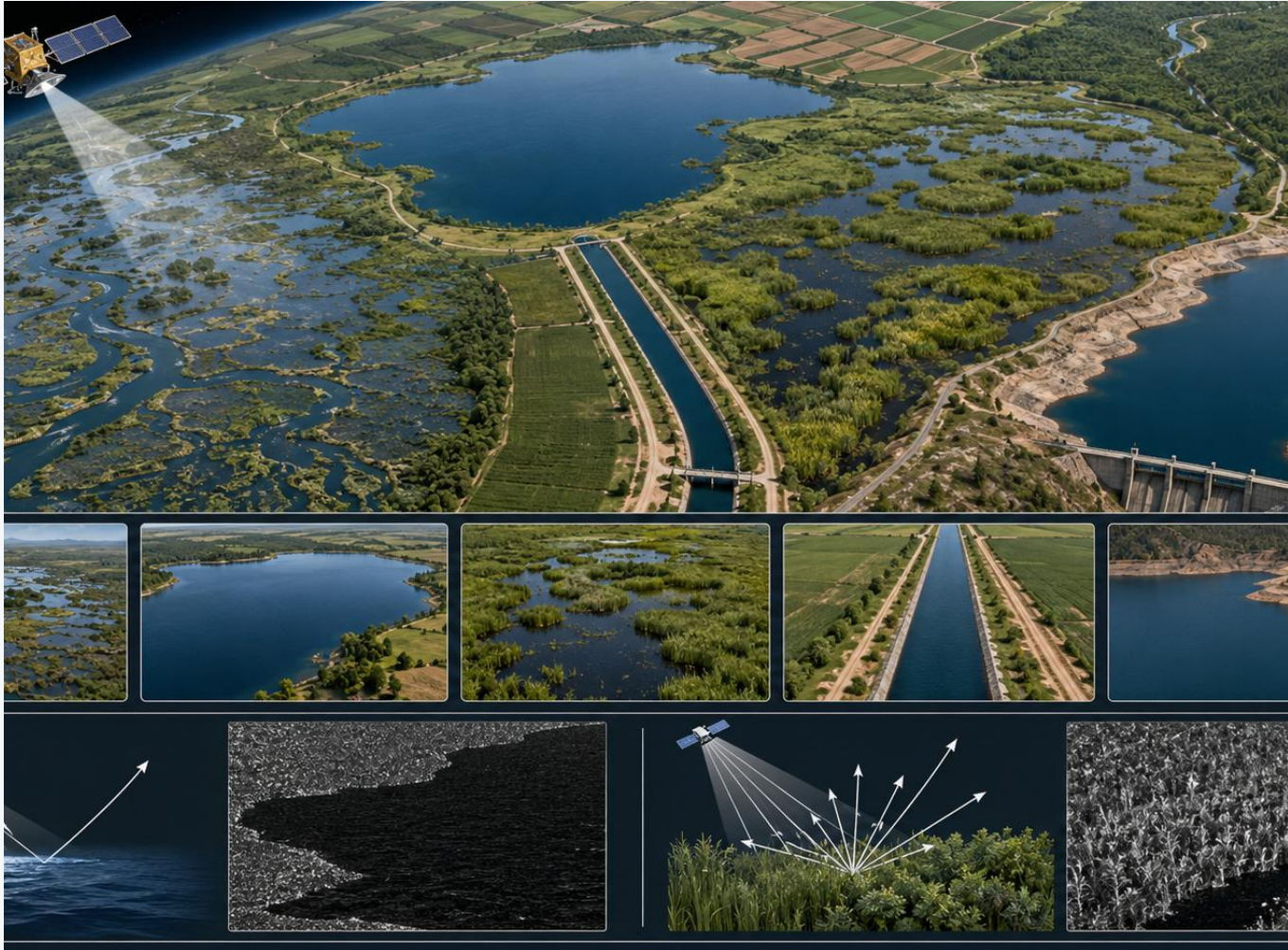
Infrastructure

settlement expansion, linear features, embankments

Terrain

LiDAR slope, aspect, drainage and micro-relief products

In land management, radar and LiDAR are often most useful when integrated with cadastre, field data, land-use maps, and GIS analysis.



Radar is strong for water extent

Smooth open water often appears dark in SAR images.
Flood mapping can be done even under clouds and at night.
Wetlands may show complex returns from water + vegetation.
Repeated images support seasonal water-change monitoring.

LiDAR supports water engineering

Detailed elevation helps analyze floodplains, canal banks, reservoir margins, drainage paths and embankment condition.



DEM / DTM

bare-earth surface for mapping
and modelling

Slope and aspect

erosion, landslide and irrigation
planning

Drainage network

flow paths, depressions and flood
routing

Deformation

radar InSAR for subsidence or
uplift over time

Radar

Works day and night.
Less affected by cloud cover than optical imagery.
Wide-area and frequent monitoring from satellites.
Sensitive to surface moisture, roughness and structure.
InSAR can detect ground deformation.

LiDAR

Very accurate 3D measurement.
Can separate ground, canopy and built structures.
Excellent for terrain models and micro-topography.
Supports engineering, forestry and flood modelling.
Produces dense, intuitive point clouds.

Radar

Speckle noise, geometric distortion, complex interpretation, polarization/incidence effects, processing knowledge needed.

LiDAR

Weather limitations, cost, flight permissions, large datasets, point classification errors, limited optical penetration.

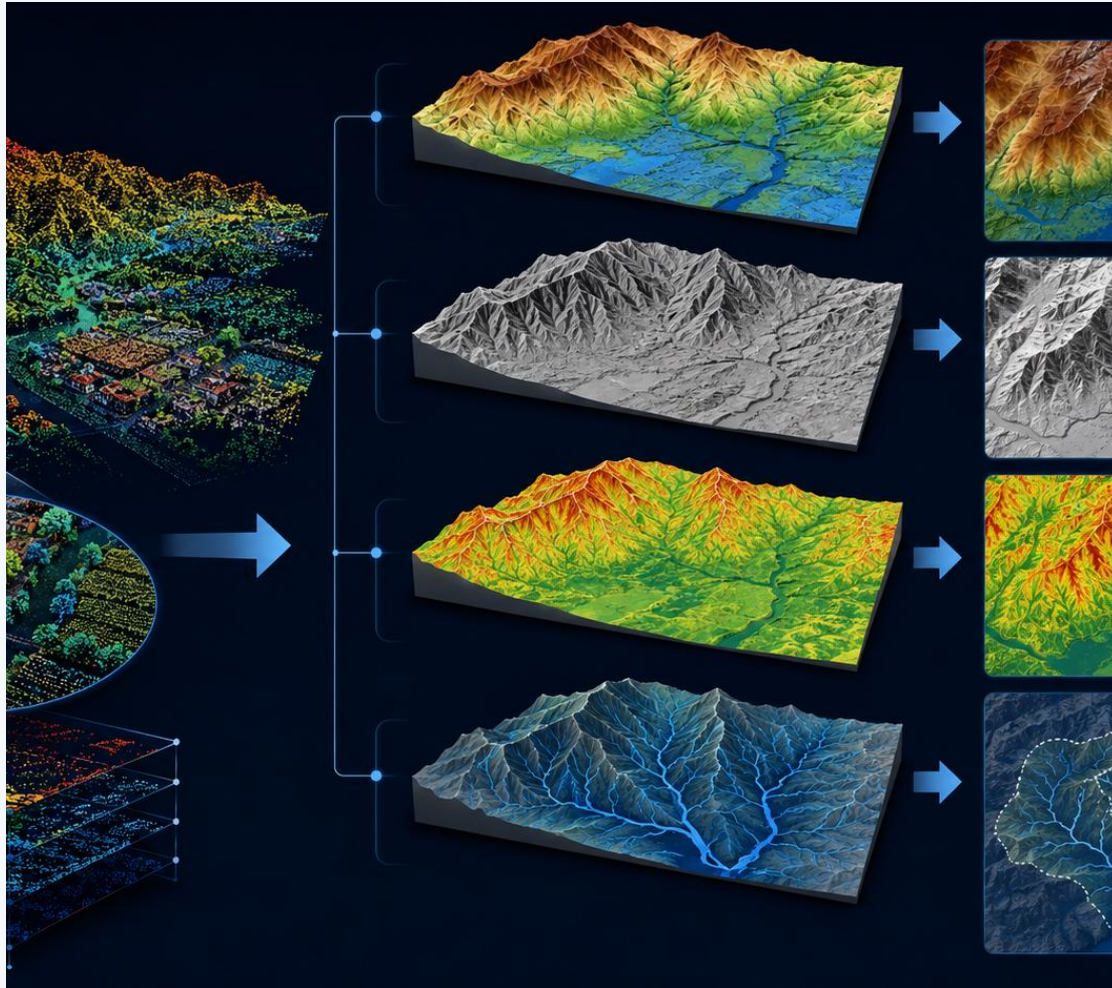
Both

Require calibration, georeferencing, quality control, field validation and clear understanding of scale.

Accuracy is not only a sensor property; it also depends on processing, terrain, atmosphere, validation data and the final application.

Decision guide: which sensor should be selected?

Need	Radar	LiDAR	Best choice	Note
Flood extent under clouds	Excellent	Limited by campaign	Radar	Add DEM
Canal-bank elevation	Indirect	Excellent	LiDAR	Engineering detail
Ground deformation	Excellent with InSAR	Not for frequent wide-area change	Radar	Needs time series
Bare-earth micro-relief	Moderate	Excellent	LiDAR	Point classification
Forest height/structure	Moderate structure clues	Excellent 3D	LiDAR	Radar complements biomass
Large routine monitoring	Strong satellite coverage	Costly if airborne	Radar	Combine with field data



1. Define question

flood risk, salinity, slope, crop monitoring, subsidence

2. Select data

SAR, LiDAR, optical, DEM, cadastre, field observations

3. Pre-process

calibration, terrain correction, classification, filtering

4. Analyze

water masks, slope maps, drainage, change detection, InSAR

5. Validate and decide

field checks, uncertainty, maps for planning or policy

Summary

Radar and LiDAR are active systems, but they measure different physical responses.
Radar is strongest for all-weather, day-night, repeated monitoring and deformation analysis.
LiDAR is strongest for accurate 3D terrain, vegetation and infrastructure mapping.
Sensor selection must follow the question, scale, budget, terrain, and validation data.
Integrated radar + LiDAR + GIS workflows give stronger evidence for land management.

References

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